



NILASAILA INSTITUTE OF SCIENCE & TECHNOLOGY  
SERGARH-756060, BALASORE (ODISHA)  
(Approved by AICTE& affiliated to SCTE&VT, Odisha)



## LESSON PLAN

**SUBJECT: Th-2 (EBNERGY CONVERSION-II)**

### CHAPTER WISE DISTRIBUTION OF PERIODS

| Sl.No. | Name of the chapter as per the Syllabus | No. of Periods as per the Syllabus | No. of periods actually needed |
|--------|---|------------------------------------|--------------------------------|
| 1      | ALTERNATOR(SYNCHRONOUS GENERATOR)       | 14                                 | 14                             |
| 2      | SYNCHRONOUS MOTOR                       | 8                                  | 11                             |
| 3      | INDUCTION MOTOR                         | 14                                 | 13                             |
| 4      | SINGLE PHASE INDUCTION MOTOR            | 8                                  | 9                              |
| 5      | COMMUTATOR MOTORS                       | 6                                  | 3                              |
| 6      | SPECIAL ELCTRICAL MACHINE               | 5                                  | 6                              |
| 7      | THREE PHASE TRANSFORMERS                | 5                                  | 4                              |
| 8      | TOTAL                                   | 60                                 | 60                             |

| Discipline:<br>ELECTRICAL<br>ENGG. | Semester:<br>5TH  | Name of the Teaching Faculty: Er. Bijaya Kumar Behera   |
|------------------------------------|---|---|
| Week                               | Class Day   | Theory Topics   |
| <b>1<sup>st</sup></b>              | <b>1<sup>st</sup></b>   | <b>ALTERNATOR:</b>  |
|                                    |   | 1.1. Types of alternator and their constructional features.   |
|                                    | <b>2<sup>nd</sup></b>   | 1.2. Basic working principle of alternator and the relation between speed and frequency.                      |
|                                    | <b>3<sup>rd</sup></b>   | 1.3. Terminology in armature winding and expressions for winding factors (Pitch factor, Distribution factor). |
| <b>2<sup>nd</sup></b>              | <b>4<sup>th</sup></b>   | 1.4. Explain harmonics, its causes and impact on winding factor.  |
|                                    | <b>1<sup>st</sup></b>   | 1.5. E.M.F equation of alternator. (Solve numerical problems).  |
|                                    | <b>2<sup>nd</sup></b>   | 1.5. E.M.F equation of alternator. (Solve numerical problems).  |
|                                    | <b>3<sup>rd</sup></b>   | 1.6. Explain Armature reaction and its effect on emf at different power factor of load.                       |
| <b>3<sup>rd</sup></b>              | <b>4<sup>th</sup></b>   | 1.7. The vector diagram of loaded alternator. (Solve numerical problems)                                      |
|                                    | <b>1<sup>st</sup></b>   | 1.7. The vector diagram of loaded alternator. (Solve numerical problems)                                      |
|                                    |   | <b>2<sup>nd</sup></b>   |
|                                    | <b>2<sup>nd</sup></b>   | 1.8.1. Open circuit test.   |
| <b>3<sup>rd</sup></b>              | 1.8.2. Short circuit test.  |   |
| <b>4<sup>th</sup></b>              | 1.9. Determination of voltage regulation of Alternator by direct loading and synchronous impedance method. (Solve numerical problems) |   |

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| <b>4<sup>th</sup></b> | <b>1<sup>st</sup></b>  | 1.10. Parallel operation of alternator using synchro-scope and dark & bright lamp method. |
|                       | <b>2<sup>nd</sup></b>  | 1.11. Explain distribution of load by parallel connected alternators.                     |
|                       | <b>3<sup>rd</sup></b>  | SYNCHRONOUS MOTOR:  |
|                       |  | 2.1. Constructional feature of Synchronous Motor.   |
| <b>4<sup>th</sup></b> | 2.2. Principles of operation, concept of load angle              |   |
| <b>5<sup>th</sup></b> | <b>1<sup>st</sup></b>  | 2.3. Derive torque, power developed.  |
|                       | <b>2<sup>nd</sup></b>  | 2.4. Effect of varying load with constant excitation.                                     |
|                       | <b>3<sup>rd</sup></b>  | 2.5. Effect of varying excitation with constant load.                                     |
|                       | <b>4<sup>th</sup></b>  | 2.6. Power angle characteristics of cylindrical rotor motor.                              |
| <b>6<sup>th</sup></b> | <b>1<sup>st</sup></b>  | 2.7. Explain effect of excitation on Armature current and power factor.                   |
|                       | <b>2<sup>nd</sup></b>  | 2.8. Hunting in Synchronous Motor.  |
|                       | <b>3<sup>rd</sup></b>  | 2.9. Function of Damper Bars in synchronous motor and generator.                          |
|                       | <b>4<sup>th</sup></b>  | 2.10. Describe method of starting of Synchronous motor.                                   |
| <b>7<sup>th</sup></b> | <b>1<sup>st</sup></b>  | 2.11. State application of synchronous motor.   |
|                       | <b>2<sup>nd</sup></b>  | THREE PHASE INDUCTION MOTOR:  |
|                       |  | 3.1. Production of rotating magnetic field.   |
|                       | <b>3<sup>rd</sup></b>  | 3.2. Constructional feature of Squirrel cage and Slip ring induction motors.              |
| <b>4<sup>th</sup></b> | 3.3. Working principles of operation of 3-phase Induction motor. |   |

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| <b>8<sup>th</sup></b>  | <b>1<sup>st</sup></b>  | 3.4. Define slip speed, slip and establish the relation of slip with rotor quantities.  |
|                        | <b>2<sup>nd</sup></b>  | 3.5. Derive expression for torque during starting and running conditions and derive conditions for maximum torque. (solve numerical problems)                     |
|                        | <b>3<sup>rd</sup></b>  | 3.6. Torque-slip characteristics.   |
|                        | <b>4<sup>th</sup></b>  | 3.7. Derive relation between full load torque and starting torque etc. (solve numerical problems)   |
| <b>9<sup>th</sup></b>  | <b>1<sup>st</sup></b>  | 3.8. Establish the relations between Rotor Copper loss, Rotor output and Gross Torque and relationship of slip with rotor copper loss. (solve numerical problems) |
|                        | <b>2<sup>nd</sup></b>  | 3.9. Methods of starting and different types of starters used for three phase Induction motor.  |
|                        | <b>3<sup>rd</sup></b>  | 3.10. Explain speed control by Voltage Control, Rotor resistance control, Pole changing, frequency control methods.   |
|                        | <b>4<sup>th</sup></b>  | 3.11. Plugging as applicable to three phase induction motor.  |
| <b>10<sup>th</sup></b> | <b>1<sup>st</sup></b>  | 3.12. Describe different types of motor enclosures.   |
|                        | <b>2<sup>nd</sup></b>  | 3.13. Explain principle of Induction Generator and state its applications.  |
|                        | <b>3<sup>rd</sup></b>  | SINGLE PHASE INDUCTION MOTOR:   |
|                        |  | 4.1. Explain Ferrari's principle.   |
| <b>4<sup>th</sup></b>  | 4.2. Explain double revolving field theory and Cross-field theory to analyze starting torque of 1-phase induction motor. |   |
| <b>11<sup>st</sup></b> | <b>1<sup>st</sup></b>  | 4.3. Explain Working principle, Torque speed characteristics, performance characteristics and application of following single phase motors.                       |
|                        | <b>2<sup>nd</sup></b>  | 4.3.1. Split phase motor.   |
|                        | <b>3<sup>rd</sup></b>  | 4.3.2. Capacitor Start motor.   |
|                        | <b>4<sup>th</sup></b>  | 4.3.3. Capacitor start, capacitor run motor.  |

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| <b>12<sup>nd</sup></b> | <b>1<sup>st</sup></b> | 4.3.4. Permanent capacitor type motor   |
|                        | <b>2<sup>nd</sup></b> | 4.3.5. Shaded pole motor.   |
|                        | <b>3<sup>rd</sup></b> | 4.4. Explain the method to change the direction of rotation of above motors.  |
|                        | <b>4<sup>th</sup></b> | <p>COMMUTATOR MOTORS:</p> <p>5.1. Construction, working principle, running characteristic and application of single phase series motor.</p> |
| <b>13<sup>rd</sup></b> | <b>1<sup>st</sup></b> | 5.2. Construction, working principle and application of Universal motors.   |
|                        | <b>2<sup>nd</sup></b> | 5.3. Working principle of Repulsion start Motor, Repulsion start Induction run motor, Repulsion Induction motor.                            |
|                        | <b>3<sup>rd</sup></b> | <p>SPECIAL ELECTRICAL MACHINE:</p> <p>6.1. Principle of Stepper motor.</p>  |
|                        | <b>4<sup>th</sup></b> | 6.2. Classification of Stepper motor.   |
| <b>14<sup>th</sup></b> | <b>1<sup>st</sup></b> | 6.3. Principle of variable reluctant stepper motor.   |
|                        | <b>2<sup>nd</sup></b> | 6.4. Principle of Permanent magnet stepper motor.   |
|                        | <b>3<sup>rd</sup></b> | 6.5. Principle of hybrid stepper motor.   |
|                        | <b>4<sup>th</sup></b> | 6.6. Applications of Stepper motor.   |
| <b>15<sup>th</sup></b> | <b>1<sup>st</sup></b> | <p><b>THREE PHASE TRANSFORMERS:</b></p> <p>7.1. Explain Grouping of winding, Advantages.</p>  |
|                        | <b>2<sup>nd</sup></b> | 7.2. Explain parallel operation of the three phase transformers.  |
|                        | <b>3<sup>rd</sup></b> | 7.3. Explain tap changer (On/Off load tap changing)   |
|                        | <b>4<sup>th</sup></b> | 7.4. Maintenance Schedule of Power Transformers.  |